





ROBOTOL[®]

The world's first robot dedicated to ear surgery

RobOtol[®] is the result of research work started in 2005 by Collin, in partnership with the team of Prof. Olivier Stekers and Prof. Yann Nguyen and the Inserm/UPMC UMR-S 1159 unit.

Technical concept

- → Mechanical architecture based on the concept of a pivot point.
- \rightarrow 7 degrees of freedom.
- → Design for otological surgeries and ergonomics adapted to the constraints of the operating room.





- First and only surgical robot in the world dedicated to otology
- 2019 First worldwide cochlear implantation (Pitié-Salpêtrière Hospital)
- > 2021 First bilateral implantation in children (CHRU Brest)
- 100% of ENT surgeries can benefit from the use of RobOtol®
- Over 1000 Cochlear Implant surgeries operated since 2019
- Over twenty equipped centers Worldwide
- > Over 70 surgeons regular users of RobOtol[®] (mid-2023)

Dedicated to ENT

Applications and performance for RobOtol®

Use of the instrument holder arm:

- → Allows access and view to all anatomical parts of the middle and inner ear with perfect stability and micrometric precision of movements for all kind of surgeries.
- → No swerves, drifts and involuntary movements of the human hand.
- → Atraumatic insertion of cochlear electrodes array in both children and adults.
- \rightarrow Perfect axis for cochlear array insertion.

Other applications planned and under development.

Use of the endoscope holder arm:

→ Allows surgeons to operate with two hands while enjoying the undeniable advantages of otendoscopy, with an extremely short learning curve.

The future directions

- \rightarrow Development of pediatric endoscopic ear surgery
- → Intraoperative monitoring of cochlear function (EcochG)
- \rightarrow Expansion to other pediatric ENT surgeries





→ Arm for MIDDLE EAR SURGERIES → Arm for INNER EAR SURGERIES → ENDOSCOPE Arm





Arms Features



Arm for MIDDLE EAR surgeries

- Dedicated Instrument
- Micrometer precision beyond human conceluities
- Reproducibility
- Safety (Atraumatic)
- Steady
- Perfect contro
- Small footprint



Arm for INNER EAR surgeries

- Decrease surgical variability by controlling the speed and acceleration of electrode insertion
- Decrease the risk of additional hearing loss or vestibular symptoms
- Micrometer precision beyond human capabilities
- Reproducibility
- Safety (Atraumatic)
- Steady
- Perfect control
- Small footprint

ENDOSCOPE Arm

- Vision and ergonomics
- Reduction of complications and recurrences
- Treatment of complex pathologies
- Safety, Precision, Stability, Reproducibility
- Two hands free
- Minimal invasive surgeries
- Rapid recovery after surgeries
- Decrease time hospitalisation
- Reduction of the learning curve for endoscopy



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